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### **Critical Sections**

- 1. Pieces of code in which you want only one process running at a time
- 2. These pieces usually access shared resources or data
- 3. Before-or-after behavior
  - Each transaction occurs either before or after each other one
- 4. Example:
  - Printer: if two print jobs enter a printer, want it to print all of one and then all of the other without interleaving pages

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## **Synchronization Objects**

- Mutexes
  - These are basically the simplest and are available to use in lab 2 (spinlocks are mutexes)
- Locks with types and semantics
  - for example, read and write locks
- Locks that unlock in order
  - for example, wait queues

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### **Mutexes**

- Two operations

```
- acquire(mutex r)
- release(mutex r)
```

- acquire
  - waits until the mutex is available, then locks it
  - any other aquiring processes continue to wait
- release
  - unlocks the mutex

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- The code base uses an osp\_spin\_lock\_t for each mutex

```
osp_spin_lock(osl);
// critical section: access shared items here
osp_spin_unlock(osl);
```

- Can use one lock to protect multiple CSs
  - Every CS protected by a given lock is locked whenever any such CS is locked
- Anything that is shared, read from, and written to probably needs to be accessed in a CS
  - And protected by locks or other synchronization mechanisms

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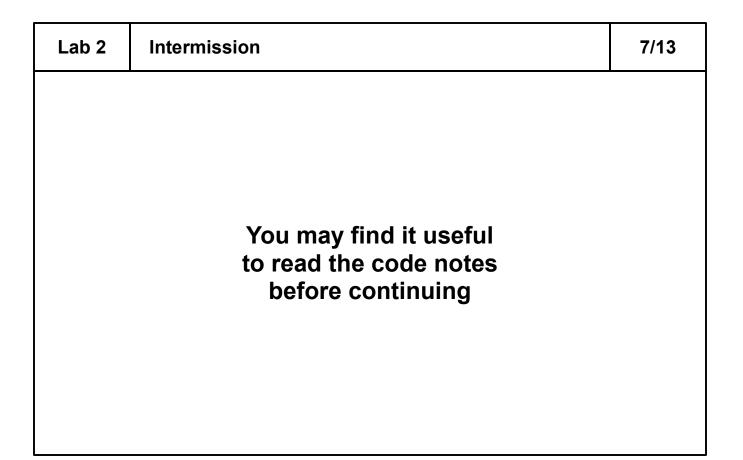
### **Counter Lock**

- Counts the number of processes waiting to get a lock on a CS
- Has three methods:
  - acquire(counterlock L)
  - release(counterlock L)
  - nwaiting(counterlock L)

## struct counterlock:

- int \_nwaiting
  - counts the number of waiting processes
- mutex wlock
  - locks access to \_nwaiting
- mutex lockb
  - locks access to the CS

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nwaiting(counterlock L):		acquire(counterlock L):	
– return Lnwaiting		<ul><li>acquire L.wlock</li><li>Lnwaiting ++</li><li>release L.wlock</li></ul>	
release(counterlock L):		- acquire L.lockb	
– release L.lockb		<ul><li>acquire L.wlock</li><li>Lnwaiting</li><li>release L.wlock</li></ul>	

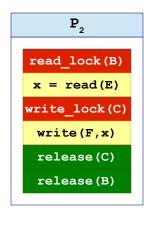


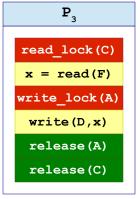
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### **Deadlock Example**

# read\_lock(A) x = read(D) write\_lock(B) write(E,x) release(B) release(A)

 $\mathbf{P}_{_{\mathbf{1}}}$ 





# **Sample Execution**

- P<sub>1</sub>. read\_lock (A)
  (gets lock on A)
- 2 P<sub>2</sub>.read\_lock(B) (gets lock on B)
- 3 P<sub>3</sub>.read\_lock(C) (gets lock on C)
- P<sub>1</sub>.write\_lock(B)
  (gets ticket on B)
- 5 P<sub>2</sub>.write\_lock(C) (gets ticket on C)
- 6 P<sub>3</sub>.write\_lock(A) (gets ticket on A)











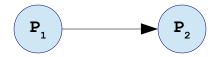


Lab 2 Deadlock II

**Dependency graph for deadlock** 

- Nodes = processes
- Edges = waits-on relation

For example,



means that  $P_1$  waits on  $P_2$ .

This is a "wait graph" rather than a precedence graph

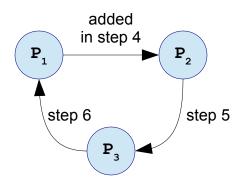
### **Convention:**

 The waiter adds the dependency (in e.g. acquire())

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- The wait<u>ee</u> frees the dependency (in e.g. release())

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Everything is fine until we add the edge  $P_3 \rightarrow P_1!$ 

# **Proposition:**

There is a deadlock situation if and only if there is a cycle in the wait graph.

Can prove under some assumptions

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### **Mutexes and Dependencies**

process p calls acquire(lock):

- gets the lock and continues;
- or doesn't get the lock, and adds edge (p→q) for q holding the lock

process q calls release(lock):

- releases the lock
- removes all (p→q) for waiters
   p (for this lock only)

Can associate each edge with a mutex

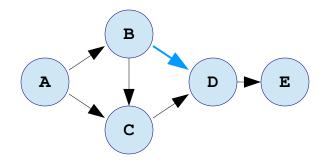
Add an edge ( $p\rightarrow q$ : r) if process p calls acquire(r) while q holds it

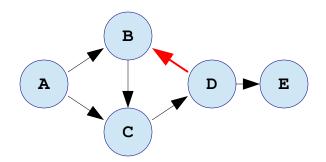
Remove all edges  $(p\rightarrow q:r)$  into q for resource r when q calls release(r)

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## **Checking for directed cycles**

- Initially, mark every node as ON
  - We turn it OFF when we know for certain that it can't be in any cycle
- Call an ON node p a NEXT node if every  $(p \rightarrow q)$  has q OFF
  - Since no one that p waits on can be in a cycle, none can wait on anyone who waits on anyone ...who waits on p
- Whenever there's a NEXT node, turn it OFF.
  - Any ON at end ⇒ cycle exists





Spin locks act like mutexes, but the read and write locks that you're implementing are a little more complicated:

- Two levels: read and write
- Must process in ticket order
- 4 (= NOSPRD) devices, each with its own read and write locks and ticketing
- What do these mean in terms of how many and what types of edges are added?

Also, there are several ways to store graphs in memory. The easiest is a list of all edges; but to look up, add, or remove an edge requires a scan of the list.